

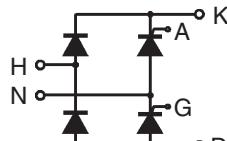
Single Phase Rectifier Bridge

$I_{dAV} = 36 A$

$V_{RRM} = 1600 V$

Preliminary data

V_{RSM}	V_{RRM}	Type
V_{DSM}	V_{DRM}	
V	V	
1700	1600	VGO 36-16io7



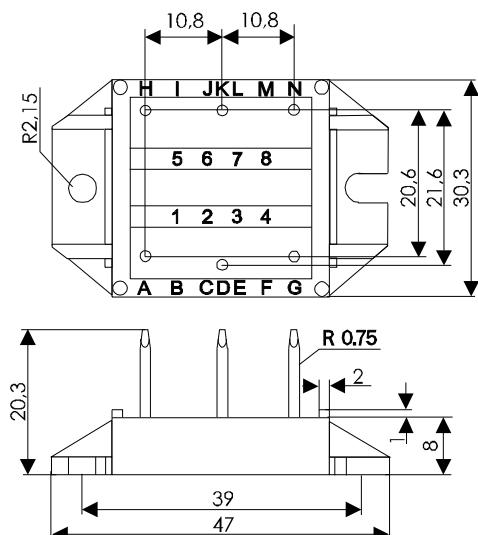
Symbol	Test Conditions	Maximum Ratings		
I_{dAV}^*	$T_H = 85^\circ C$, module	36	A	
I_{dAVM}^*	module	40	A	
I_{FRMS}, I_{TRMS}	per leg	31	A	
I_{FSM}, I_{TSM}	$T_{VJ} = 45^\circ C$; $V_R = 0 V$	320	A	
	$t = 10 \text{ ms (50 Hz), sine}$ $t = 8.3 \text{ ms (60 Hz), sine}$	350	A	
	$T_{VJ} = T_{VJM}$ $V_R = 0 V$	280	A	
	$t = 10 \text{ ms (50 Hz), sine}$ $t = 8.3 \text{ ms (60 Hz), sine}$	310	A	
I^{2t}	$T_{VJ} = 45^\circ C$ $V_R = 0 V$	500	$A^2 s$	
	$t = 10 \text{ ms (50 Hz), sine}$ $t = 8.3 \text{ ms (60 Hz), sine}$	520	$A^2 s$	
	$T_{VJ} = T_{VJM}$ $V_R = 0 V$	390	$A^2 s$	
	$t = 10 \text{ ms (50 Hz), sine}$ $t = 8.3 \text{ ms (60 Hz), sine}$	400	$A^2 s$	
$(di/dt)_{cr}$	$T_{VJ} = 125^\circ C$ $f = 50 \text{ Hz}, t_p = 200 \mu s$ $V_D = 2/3 V_{DRM}$ $I_G = 0.3 A$, $di_G/dt = 0.3 A/\mu s$	repetitive, $I_T = 50 A$	150	$A/\mu s$
		non repetitive, $I_T = 1/2 \cdot I_{dAV}$	500	$A/\mu s$
$(dv/dt)_{cr}$	$T_{VJ} = T_{VJM}; V_{DR} = 2/3 V_{DRM}$ $R_{GK} = \infty$; method 1 (linear voltage rise)		1000	$V/\mu s$
V_{RGM}			10	V
P_{GM}	$T_{VJ} = T_{VJM}$ $I_T = I_{TAVM}$	$t_p = 30 \mu s$ $t_p = 500 \mu s$ $t_p = 10 ms$	≤ 10 ≤ 5 ≤ 1	W
P_{GAVM}			0.5	W
T_{VJ}			-40...+125	$^\circ C$
T_{VJM}			125	$^\circ C$
T_{stg}			-40...+125	$^\circ C$
V_{ISOL}	50/60 Hz, RMS $I_{ISOL} \leq 1 mA$	$t = 1 \text{ min}$ $t = 1 s$	2500 3000	V~
M_d	Mounting torque (M4)		1.5 - 2 14 - 18	Nm lb.in.
Weight	typ.		18	g

Data according to IEC 60747 refer to a single diode/thyristor unless otherwise stated

* for resistive load at bridge output. IXYS reserves the right to change limits, test conditions and dimensions.

Symbol	Test Conditions	Characteristic Values		
I_R, I_D	$V_R = V_{RRM}; V_D = V_{DRM}$ $T_{VJ} = T_{VJM}$ $T_{VJ} = 25^\circ C$	≤ 5 mA	≤ 0.3 mA	
V_T, V_F	$I_T, I_F = 45 A; T_{VJ} = 25^\circ C$	≤ 1.45 V		
V_{TO}	For power-loss calculations only ($T_{VJ} = 125^\circ C$)	0.85 V		
r_T		13 mΩ		
V_{GT}	$V_D = 6 V;$ $T_{VJ} = 25^\circ C$ $T_{VJ} = -40^\circ C$	≤ 1.0 V	≤ 1.2 V	
I_{GT}	$V_D = 6 V;$ $T_{VJ} = 25^\circ C$ $T_{VJ} = -40^\circ C$ $T_{VJ} = 125^\circ C$	≤ 65 mA	≤ 80 mA	≤ 50 mA
V_{GD}	$T_{VJ} = T_{VJM};$ $T_{VJ} = T_{VJM};$	$V_D = 2/3 V_{DRM}$	≤ 0.2 V	
I_{GD}		$V_D = 2/3 V_{DRM}$	≤ 5 mA	
I_L	$I_G = 0.3 A; t_g = 30 \mu s;$ $di_g/dt = 0.3 A/\mu s;$ $T_{VJ} = 25^\circ C$ $T_{VJ} = -40^\circ C$ $T_{VJ} = 125^\circ C$	≤ 150 mA	≤ 200 mA	≤ 100 mA
I_H	$T_{VJ} = 25^\circ C; V_D = 6 V; R_{GK} = \infty$	≤ 100 mA		
t_{gd}	$T_{VJ} = 25^\circ C; V_D = 1/2 V_{DRM}$ $I_G = 0.3 A; di_g/dt = 0.3 A/\mu s$	≤ 2 μs		
t_q	$T_{VJ} = 125^\circ C, I_T = 15 A, t_p = 300 \mu s, V_R = 100 V$ $di/dt = -10 A/\mu s, dv/dt = 20 V/\mu s, V_D = 2/3 V_{DRM}$	typ. 150 μs		
R_{thJC}	per thyristor (diode); DC current	1.4 K/W		
	per module	0.35 K/W		
R_{thJK}	per thyristor (diode); DC current	2.0 K/W		
	per module	0.5 K/W		
d_s	Creepage distance on surface	12.6 mm		
d_A	Creepage distance in air	6.3 mm		
a	Max. allowable acceleration	50 m/s²		

Dimensions in mm (1 mm = 0.0394")



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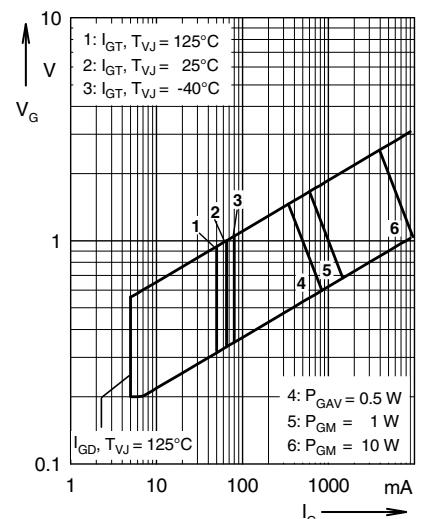


Fig. 1 Gate trigger range

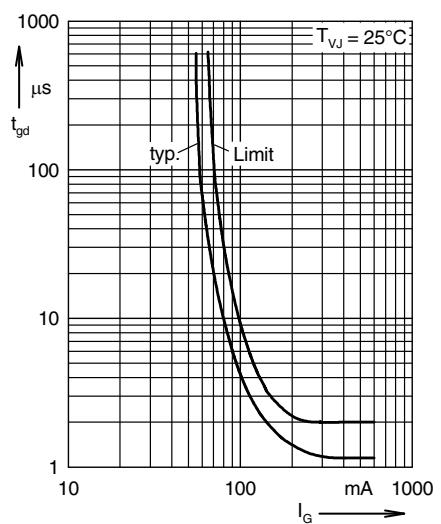


Fig. 2 Gate controlled delay time t_{gd}